

# USER MANUAL



SOFTWARE VITDRIVE V1.0.0

**SALICRU**

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## I. General

The manual describes the operation procedure of VITdrive monitor system which is used to configure and monitor ControlVIT series inverters.

Currently, all ControlVIT inverters support serial Modbus protocol. Operation control and parameter modification via upper computer is intuitive and easy-to-use.

VITdrive software supports:

- ★ All models of ControlVIT inverters;
- ★ Serial communication;
- ★ Monitoring multiple and various inverters: One computer monitors multiple and various inverters at the same time;
- ★ Uploading and downloading parameters, importing and exporting parameter files;
- ★ Modifying and viewing parameters;
- ★ Bit monitoring, read and write for status word and control word of function codes;
- ★ Inverter parameter oscillography;
- ★ Fault diagnosis and cause prompt;
- ★ Inverter start/stop, FWD/REV running control and fault reset;
- ★ Parameter online help;
- ★ Flexible configuration of function codes: With strong generality, the software is compatible with the function codes of standard and non-standard software.

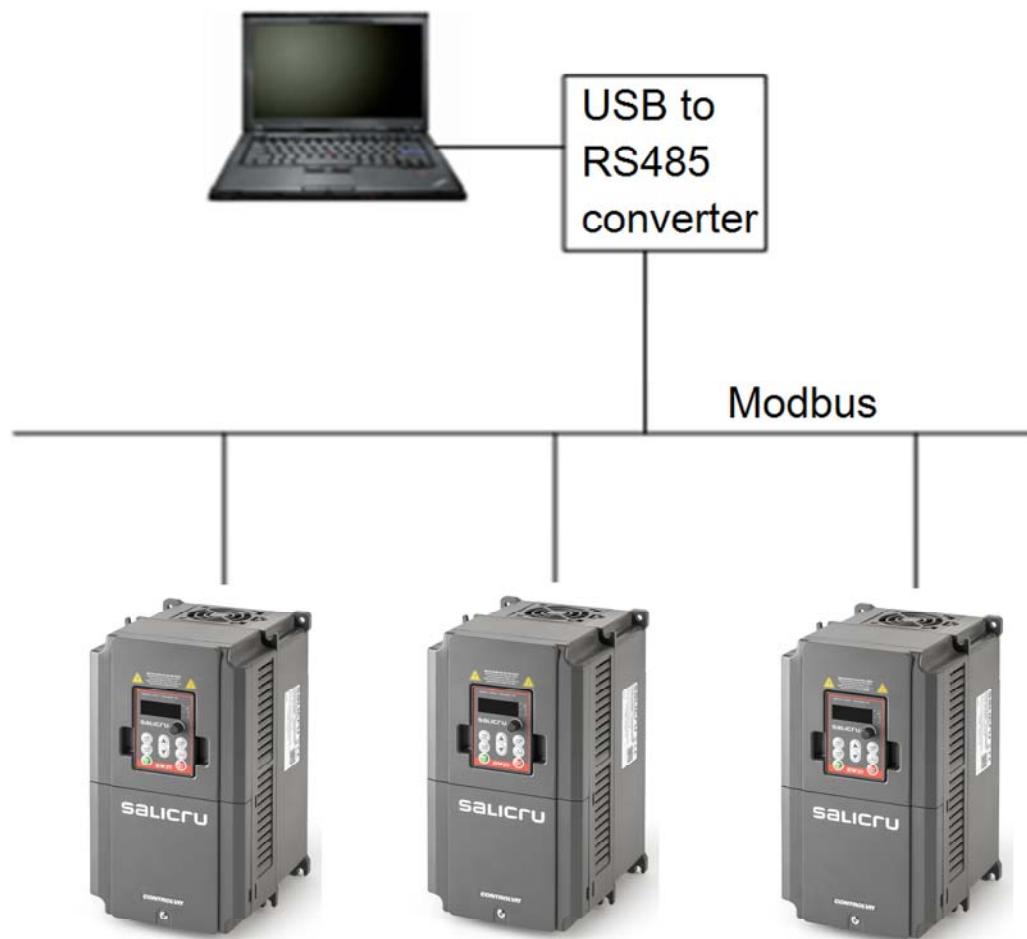
## II. Use of VITdrive

### 2.1 Hardware connection

1. Serial communication: The inverters are equipped with RS485 interface while PCs are generally equipped with USB interface. So a USB-to-RS485 converter must be connected at the PC side. Then, connect via twisted pair (0-5kM). The interface connection mode is as shown in the table below:

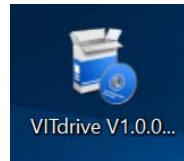
Interface of the USB-to-RS485 converter	Interface of the inverter	Interface of the USB-to-RS485 converter	Interface of the inverter
R-(D-)	485-	R+(D+)	485+

The structure diagram of system connection is shown below:



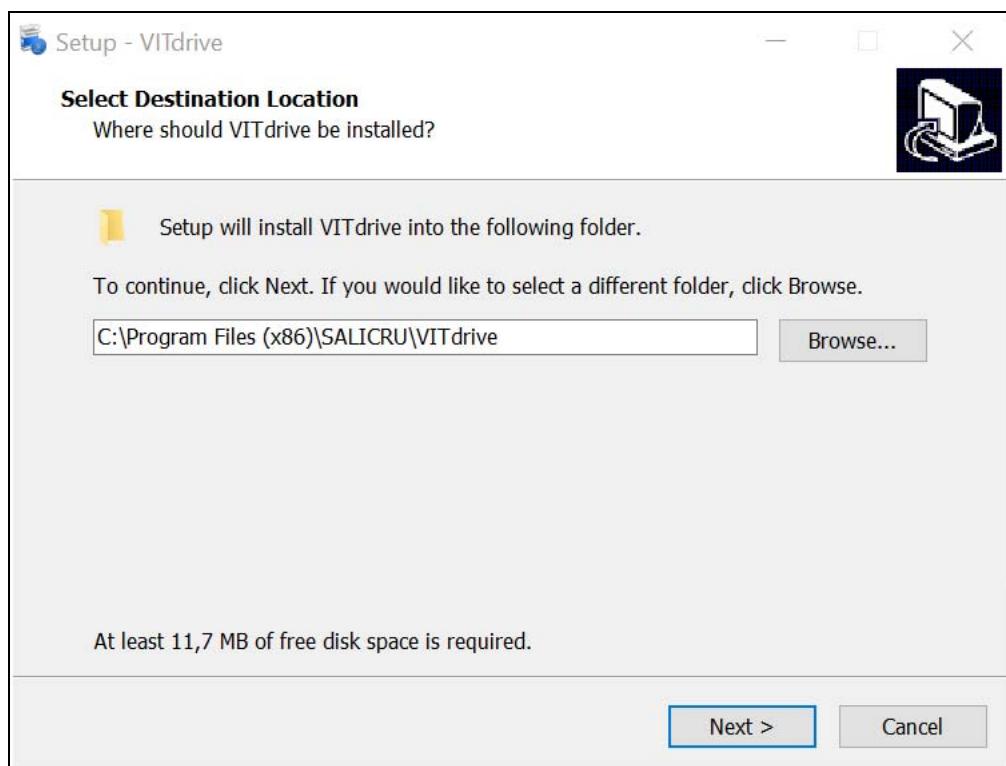
## 2.2 Software installation

### 1. Run VITdrive Setup.exe

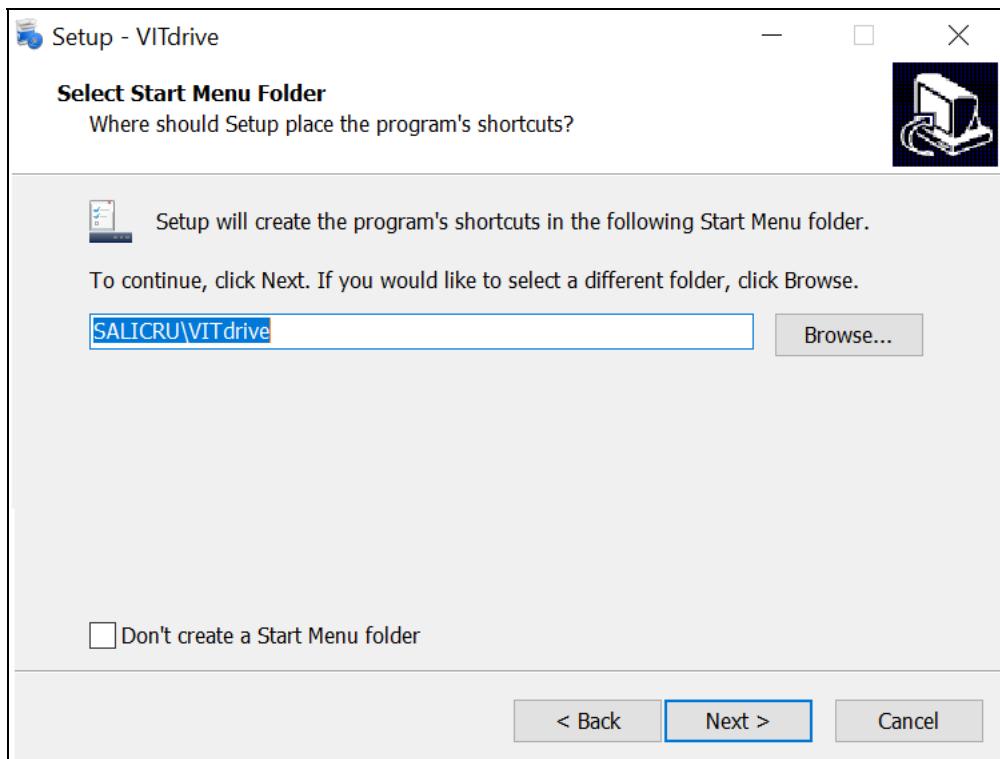


Pop up the setup wizard.

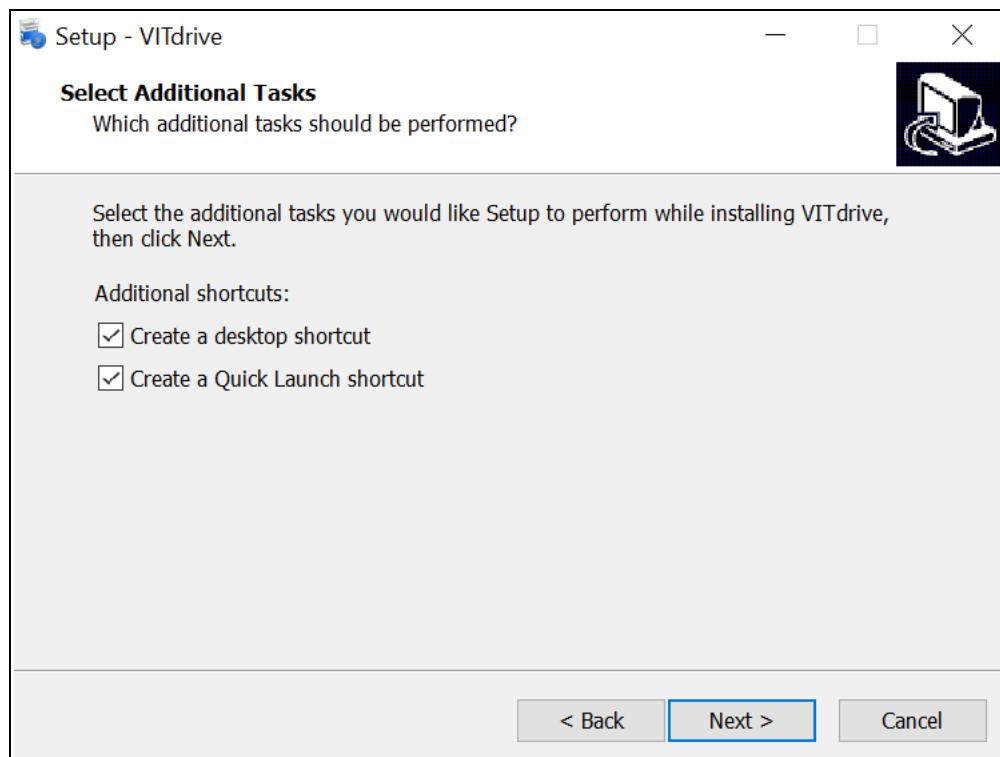
### 2. Click Next to enter the page of Select Destination Location. VITdrive will be installed by default in the directory C:\Program Files\ SALICRU \ VITdrive.



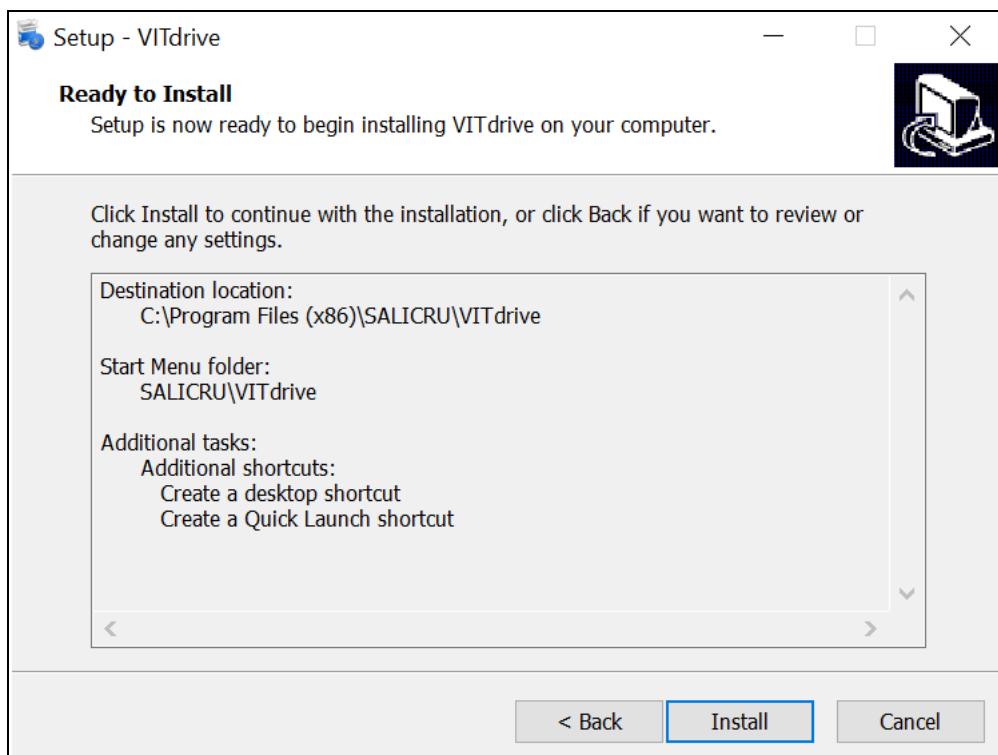
3. Click Next to enter the page of Select Start Menu Folder and specify the path.



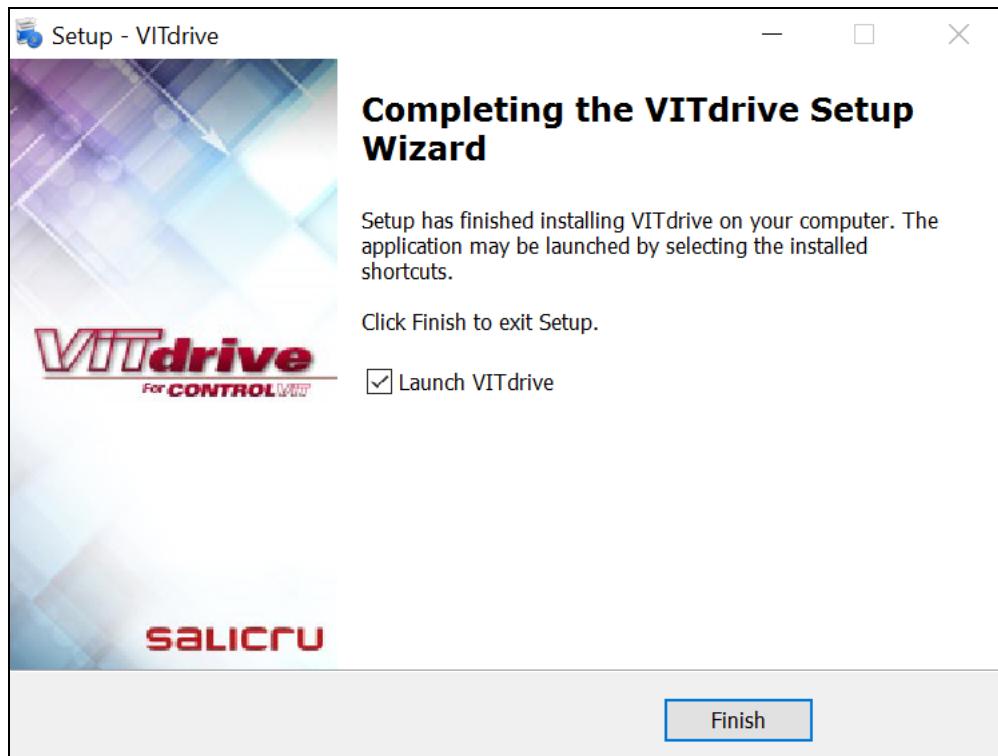
4. Click Next to enter the page of Select Additional Tasks and decide whether to create shortcuts as needed.



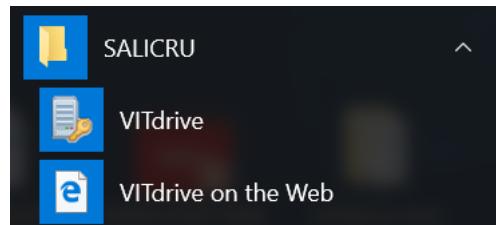
5. Click Next to enter the page of Ready to Install.



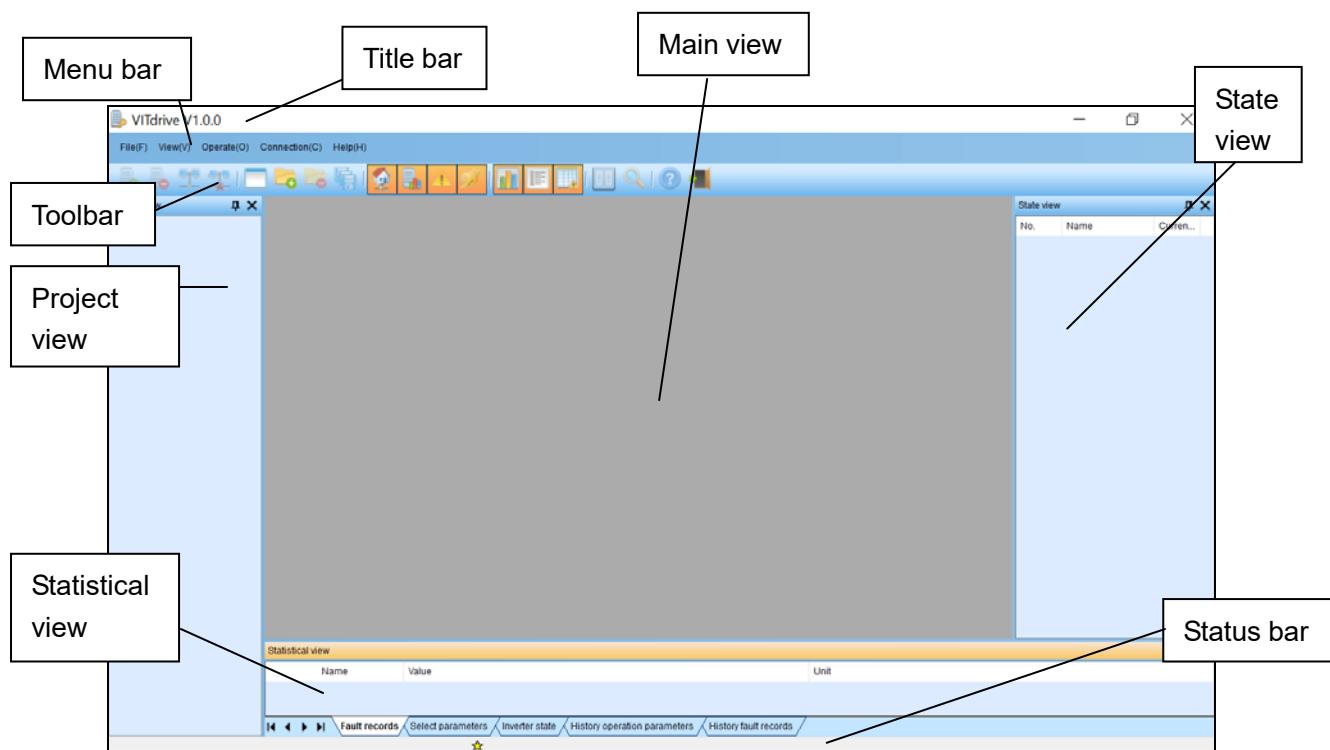
6. Click Install. The setup wizard will prompt Finish after software installation is completed.



7. After installation, a quick launch icon of VITdrive will be created on the desktop and simultaneously in start menu.

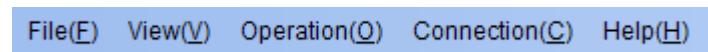


### III. Software interface

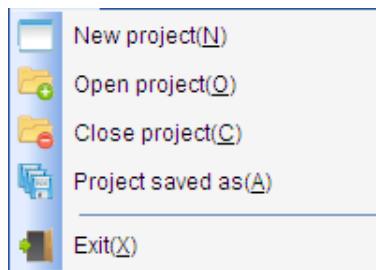


Name	Function
Title bar	Display the name of software
Menu bar	Provide the menu options for each operation
Toolbar	Place the commonly used menus for ease of operation
Status bar	Prompt inverter connection states, read and write errors of function parameters, etc.
Main view	Oscilloscope, function codes, control panel
Project view	Display and manage the inverter
State view	Display running parameters of the inverter
Statistical view	Display fault records, select parameters, inverter states, history records

### 3.1 Menu bar

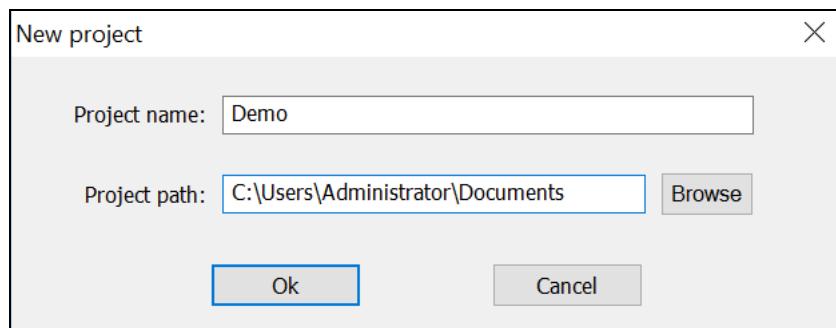


#### 3.1.1 File

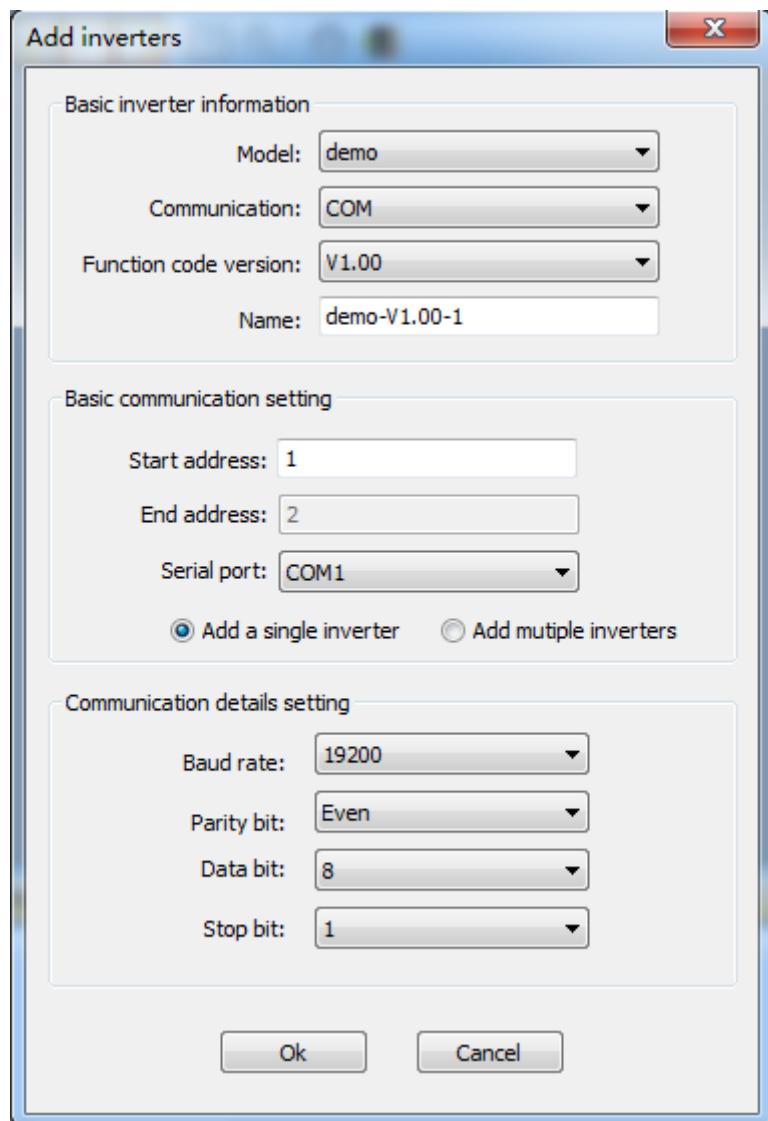


##### ★ New project

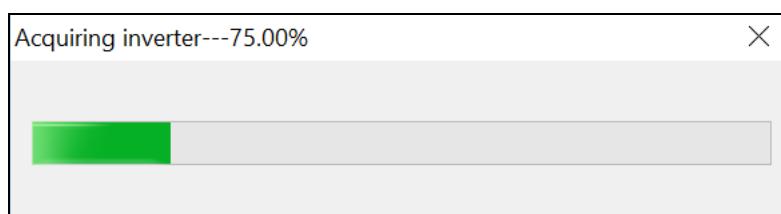
Step 1, input project name and project path.



Step 2, add inverters: select inverter model and communication method. For serial communication, users need to confirm the slave address, serial port number, baud rate, check mode, data length, start and end bit, etc.



Step 3, add a single inverter or multiple inverters. If users select the option of Add multiple inverters, the software will search the connected inverters automatically.



#### ★ Open project

Open the created project in file extension \*.ipj.



### ★ Close project

Close the current opened project.

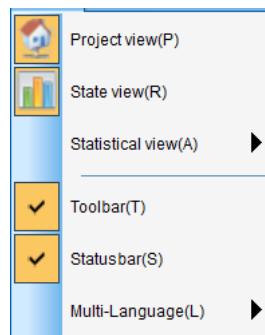
### ★ Save as

Save the project as another path or name.

### ★ Exit

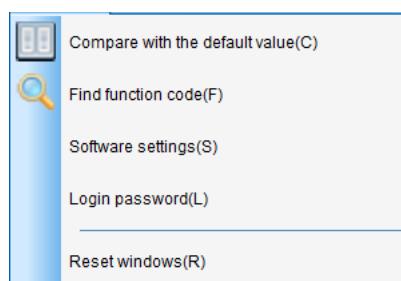
Exit the software.

## 3.1.2 View



Show or hide the windows at all levels.

## 3.1.3 Operation



### ★ Compare with the default value

Compare the current value with the default value of inverter parameters and then pick out different values. The left is the current value and the right is the compared result.

Compare

Serial number	Name	Current value	Default
P00 Basic function group			
P01 Start-up and stop control			
P02 Motor 1			
P03 Vector control			
P04 V/F control			
P05 Input terminals			
P06 Output terminals			
P07 Human-Machine Interface			
P08 Enhanced function			
P09 PID control			
P10 Simple PLC and multi-stage s...			
P11 Protective parameters			
P13 Synchronous motor control			
P14 Serial communication			
P00 Basic function group			
P01 Start-up and stop co...			
P02 Motor 1			
P04 V/F control			
P05 Input terminals			
P06 Output terminals			
P07 Human-Machine Int...			
P08 Enhanced function			
<b>P09 PID control</b>			
P10 Simple PLC and mu...			
P11 Protective parameters			
P13 Synchronous motor ...			

Compare with the default value      Cancel

### ★Find function code

Input the keyword to find the location of function codes in the list of function parameters.

Find

Keyword:

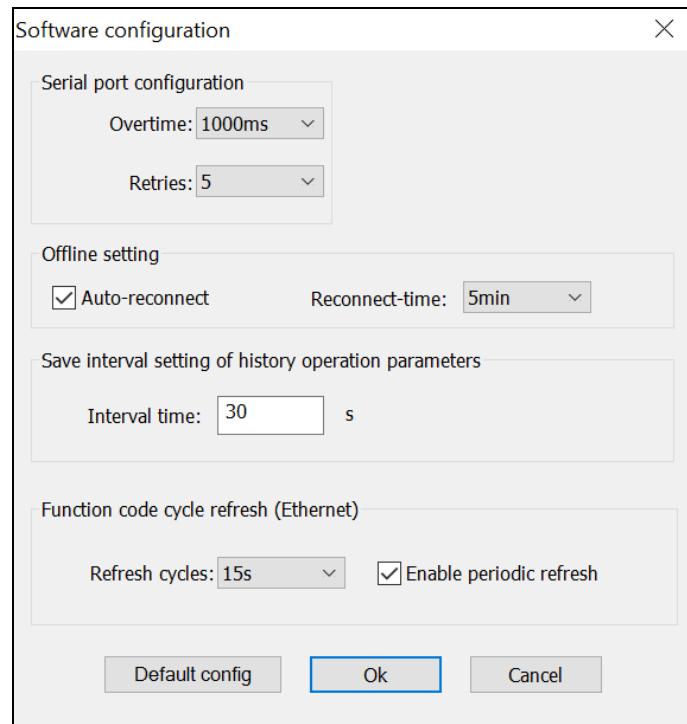
Find next(N)      Cancel

Direction

Up       Down

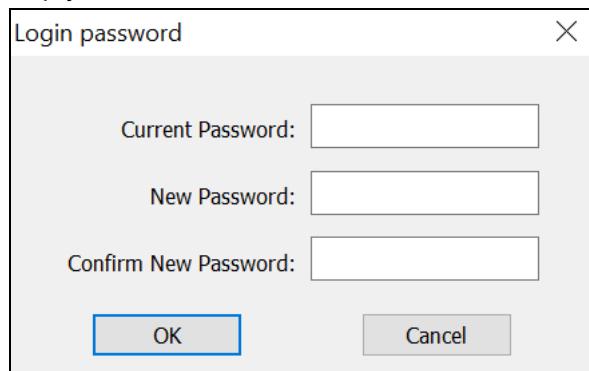
### ★Software settings

Set the basic parameters of serial port, including the time of communication overtime, the number of retries, etc.



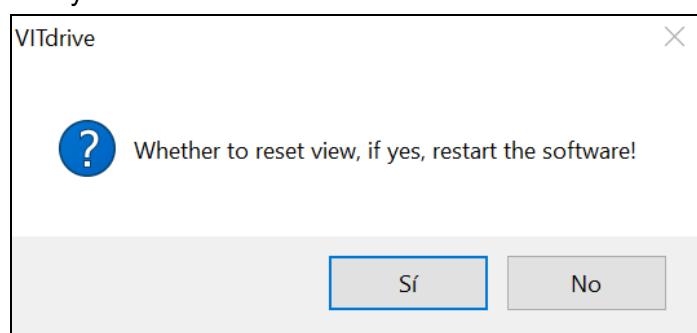
#### ★ Login password

Set the login password for starting the software. Software is no password by default, the original password is empty.

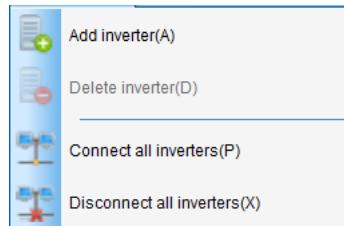


#### ★ Reset window

Restore the default layout when the window of VITdrive is cluttered.



### 3.1.4 Connection



#### ★Add inverters

Add new inverters.

#### ★Delete inverters

Delete the added inverters.

Delete inverters					
No.	Name	Model	Communication	Address	Online situation
<input type="checkbox"/> 1	CV10-V1.00-1	CV10	Serial port	COM1-1	Offline
<input type="checkbox"/> 2	CV30-V1.00-2	CV30	Serial port	COM1-2	Offline

Ok Cancel All select All delete

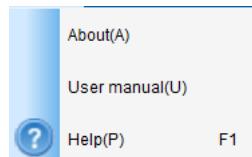
#### ★Connect all inverters

Connect all inverters.

#### ★Disconnect all inverters

Disconnect all inverters.

### 3.1.5 Help



About: Software version and copyright statements

User manual: The operation of the software

Help: Query function code

### 3.2 Toolbar



The function of each toolbar button can be found in menu bar. Users can operate these buttons as shortcuts.

### 3.3 Status bar

Model: CV30\_V1.00 Site address:1 Commu:serial port Error types: Check error! data address:4384

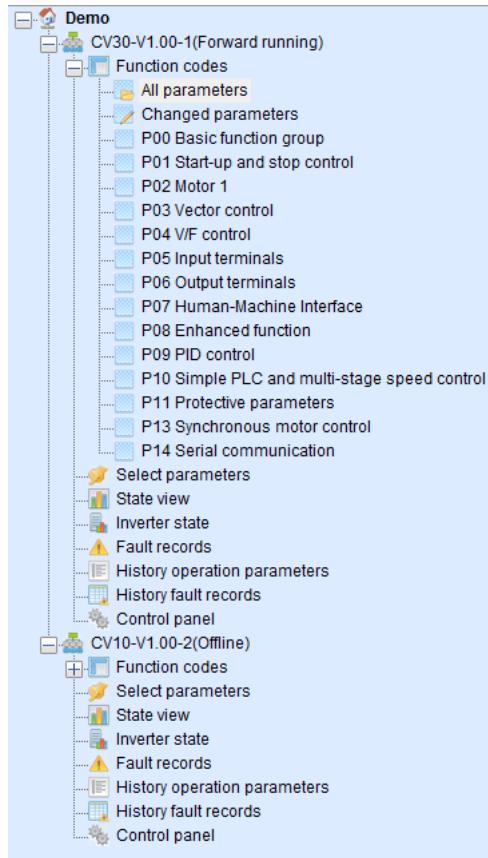
Prompt inverter connection states, read and write errors of function parameters, etc.

### 3.4 Main view

Select	No.	Name	Current value	Min	Max	Default	Unit
P00 Basic function group							
P01 Start-up and stop control							
P02 Motor 1							
P03 Vector control							
P04 V/F control							
P05 Input terminals							
P06 Output terminals							
P07 Human-Machine Interface							
P08 Enhanced function							
P09 PID control							
P10 Simple PLC and multi-sta..							
P11 Protective parameters							
P13 Synchronous motor control							
P14 Serial communication							

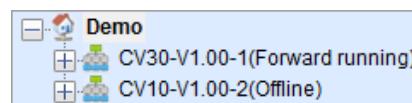
The main view is divided into three subpages, oscilograph, function codes and control panel, in charge of corresponding functions. For specific information, please refer to following chapters.

### 3.5 Project view



List a large quantity of inverter monitoring information, including project name, inverter identity, list of function parameters, select parameters, state view, inverter state, fault records, history operation parameters, history fault records, control panel, etc.

In order to monitor multiple inverters, the project view will list the added inverters. Users can switch inverters by double-click the names.



### 3.6 State view

No.	Name	Current...
P17.00	Set frequency	29.15
P17.01	Output frequency	29.15
P17.02	Ramp given frequ...	29.15
P17.03	Output voltage	128
P17.04	Output current	0.0
P17.05	The rotation speed ...	874
P17.06	Torque current	0.0
P17.07	Magnetized current	0.0
P17.08	Motor power	-2.7
P17.09	Output torque	-22.0
P17.10	The motor frequenc...	0.00
P17.11	DC bus voltage	329.8
P17.12	Switch input termin...	0
P17.13	Switch output termin...	4
P17.14	Digital adjustment	0.00
P17.15	Torque given	0.0
P17.16	Linear speed	8
P17.17	Reserved	0
P17.18	Counting value	0
P17.19	AI1 input voltage	6.00
P17.20	AI2 input voltage	0.00
P17.21	AI3 input voltage	0.01
P17.22	HDI input frequency	0.00
P17.23	PID given value	0.0
P17.24	PID response value	0.0
P17.25	Power factor of the ...	1.00
P17.26	Current running time	36
P17.27	Simple PLC and the..	0

Display inverter operation parameters. In normal communication, the data are refreshed at real time. The refresh cycle is 1s for serial communication.

### 3.7 Statistical view

Name	Value	Unit
Time	Offline time:10:46:50	
Fault	Unknown	
Current fault running frequency	Unknown	Hz
Ramp given frequency at curre...	Unknown	Hz
Output voltage at the current fa...	Unknown	V
Current fault output current	Unknown	A
Current fault bus voltage	Unknown	V
The Max temperature at Curre...	Unknown	℃

#### ★ Fault records

Record current inverter fault information, such as current fault time, fault code, fault running frequency, fault ramp reference frequency, output voltage, output current, bus voltage, input and output terminals state, etc.

#### ★ Select parameters

Select	No.	Name
<input checked="" type="checkbox"/>	P06.01	Y output selection
<input checked="" type="checkbox"/>	P05.00	HDI input type selection
<input checked="" type="checkbox"/>	P04.00	Motor 1V/F curve setting

Tick the commonly used function codes as select parameters to enhance the efficiency of

modifying function codes. Users can directly operate function codes in statistical view.

★ Inverter state

Display current inverter connection state and fault type.

★ History operation parameters

Record inverter history operation parameters in details. Users can view them according to specified date.

★ History fault records

Record inverter history fault records in details. Users can view them according to specified date.

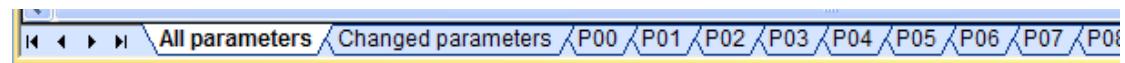
## IV. Inverter parameters

### 4.1 View function codes

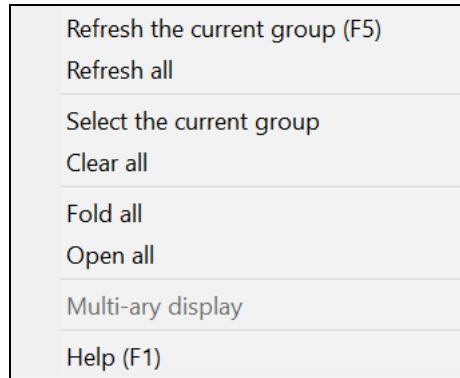
The main window of function parameters lists all function codes, including group, No., name, current value, maximum value, minimum value, default value and unit.

Select	No.
	P00 Basic function group
	P01 Start-up and stop control
	P02 Motor 1
	P03 Vector control
	P04 V/F control
	P05 Input terminals
	P06 Output terminals
	P07 Human-Machine Interface
	P08 Enhanced function
	P09 PID control
	P10 Simple PLC and multi-sta..
	P11 Protective parameters
	P13 Synchronous motor control
	P14 Serial communication

The tab also provides the shortcut index for each group.



The function parameters cannot refresh automatically, so users need to refresh them manually. Right click in the display view of function codes and pop up the following menu.

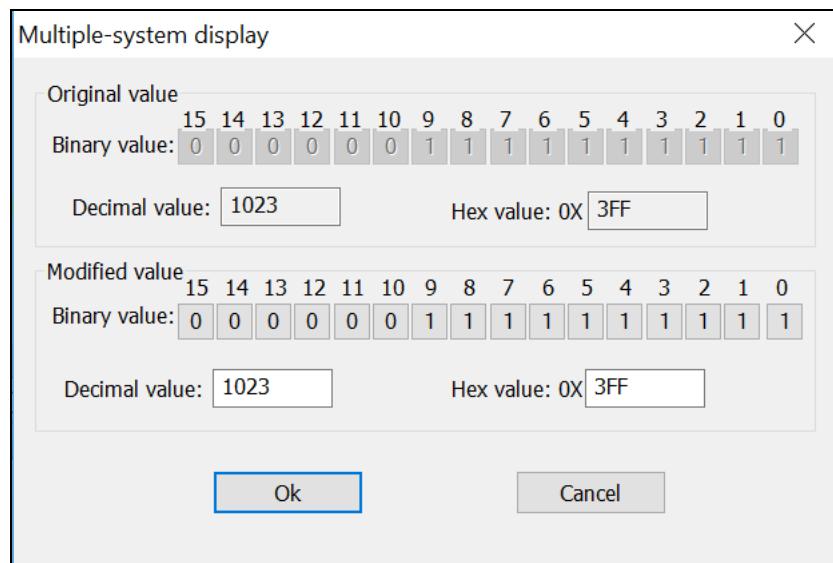


Select Refresh current group or Refresh all as required;

Select current group/Clear all: Tick the commonly used function codes as select parameters;

Close all tree/Open all tree: Unfold or fold the parameters tree;

Multiple-system display: Support bit monitoring, read and write for status word and control word of function codes;



Help: View specific instructions of the current group.

## 4.2 Modify function codes

Each function code has corresponding icon which indicates:

Icon	Description
	The parameters can be read or written in any condition.
	The parameter is not writable.
	This parameter is not writable but readable.
	The parameter is not writable or readable.
	This parameter is not readable but writable.

Double click the function code and pop up the modify box.

(1) If the function code is enumeration type, pop up the drop-down box. Finish setting by selecting corresponding item.

P00.01	Run command channel	2:Communication running comm: 0
P00.02	Communication running commands..	0:Keypad running command channel
P00.03	Max.output frequency	1:Terminal running command channel
P00.04	Upper limit of the running frequency	2:Communication running command channel

(2) If the function code is numeric type, pop up the edit box. Finish setting by clicking the margin after filling in numbers in the box.

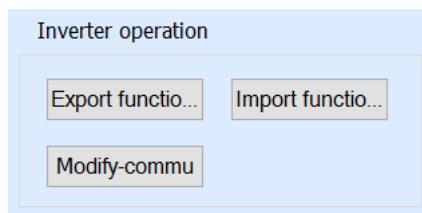
P00.03	Max.output frequency	50.00
--------	----------------------	-------

Note: Recent modified function codes can be viewed in the page of modified parameters.

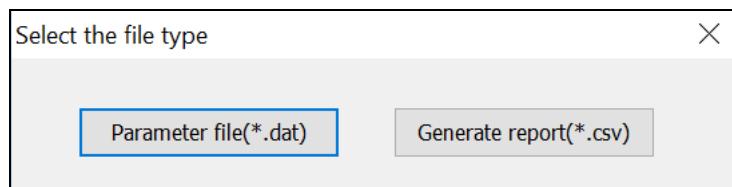
Select	No.	Name	Value after modification	Value before modification	Modify the time
<input checked="" type="checkbox"/>	P00.03	Max.output frequency	20.00	50.00	2013-07-11 10:54:31
<input checked="" type="checkbox"/>	P00.08	B frequency command ref..	1:A frequency command	0:Maximum output frequency	2013-07-11 10:54:27
<input checked="" type="checkbox"/>	P00.06	A frequency command se...	4:High-speed pulse HDI	0:Keypad data setting	2013-07-11 10:54:25

#### 4.3 Import and export function codes

Users can see the interface of inverter operation after entering the main window of control panel page.

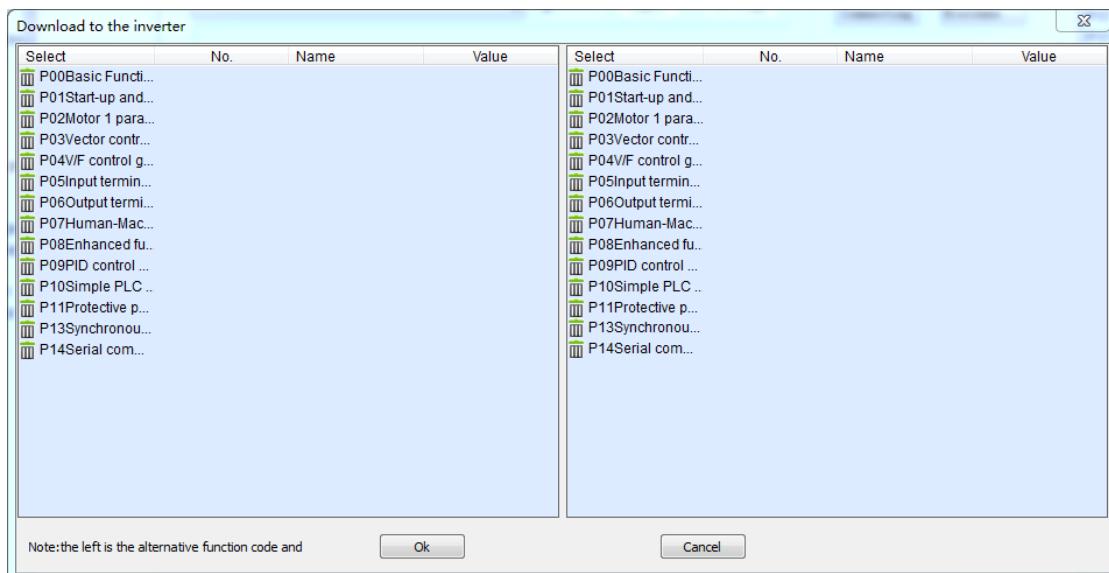


1. Export function codes: Save the function codes in different file types as needed. The parameter file (\*.dat) is self-defined in binary format; the report file (\*.csv) is comma-separated file which can be opened by Microsoft Office Excel.

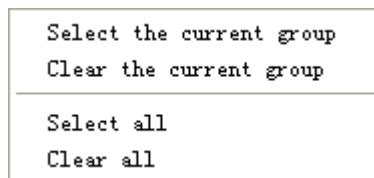


2. Import function codes: Import the saved binary file (\*.dat) to the current inverter in connection.

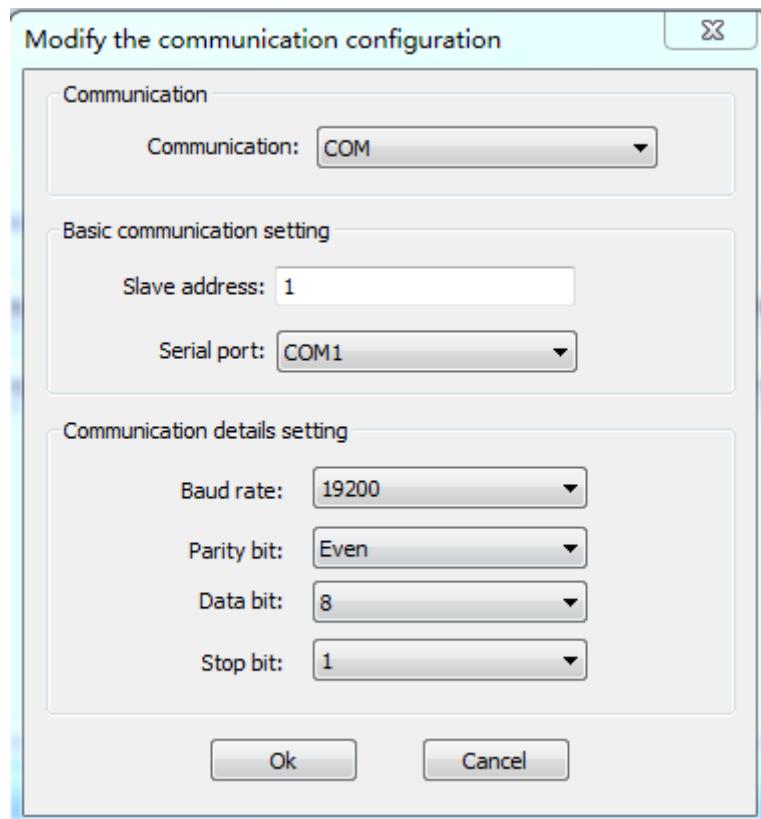
Open the existed file and pop up the following dialog box. The left is the alternative function codes and the right is the selected function codes. The function codes are user-defined and users can select them as needed.



Right click the margin and pop up the following menu for the convenience of selecting or clearing function code groups.

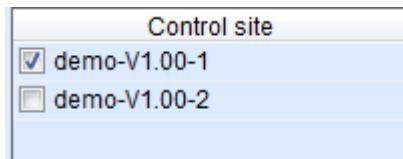


3. Modify communication configuration: Flexibly configure the current communication method without reestablishment.

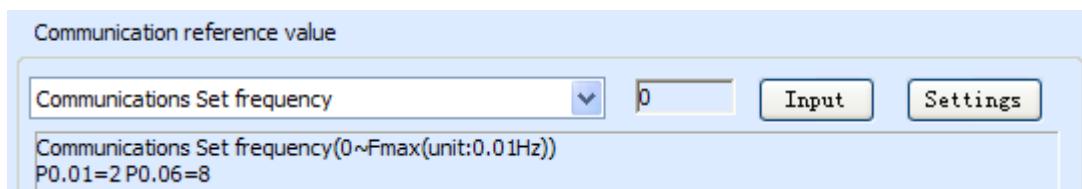


## V. Inverter control

Ensure the site before inverter control:



1. Communication reference value: The value can be set in control panel page.



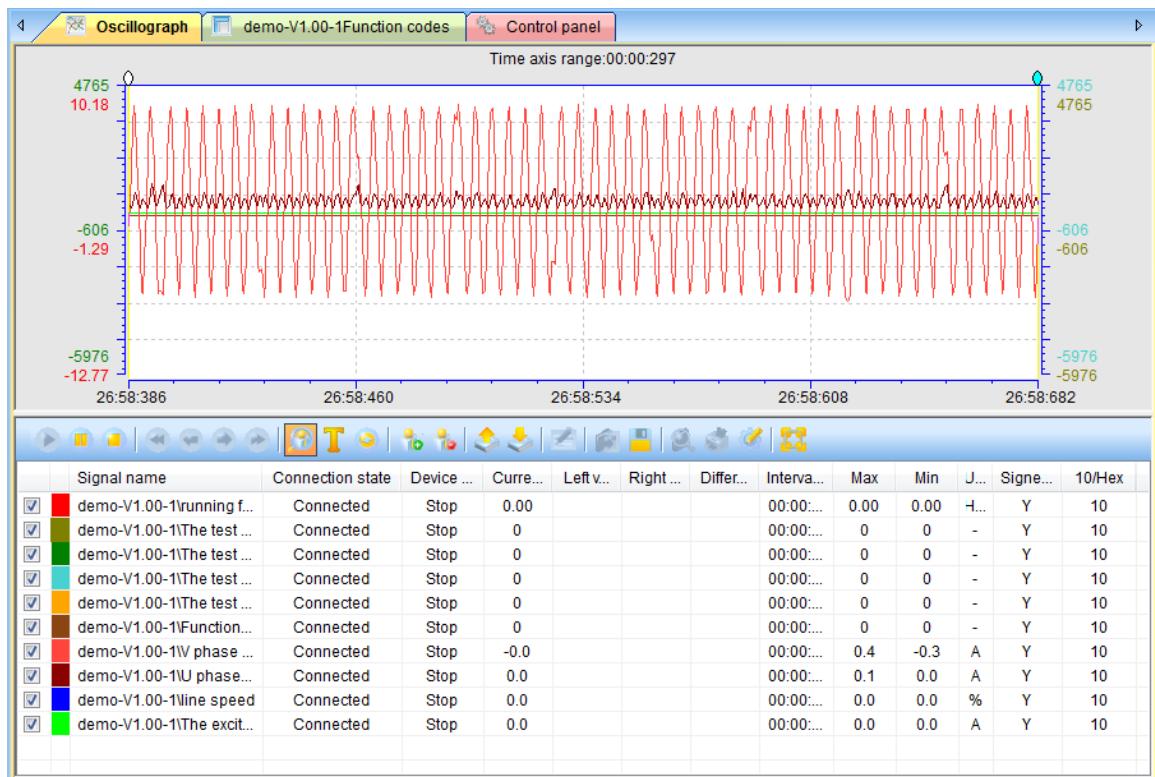
2. Operation control: To enable operation control, set running command channel to communication command channel. For example, set P00.01 to 2 for Modbus communication. Note: Due to the differences between different models of inverter operation control command, so button control panel design is different. For example, such as "Pre-excitation" button in some type of inverter doesn't exist.



## VI. Inverter oscilloscope

### 6.1 Oscilloscope interface

The oscilloscope takes charge of collecting inverter data and shows the data in waveforms, for the convenience of monitoring and analyzing operation data. The interface consists of two sections: signal drawing view and signal management view.



Name	Function																											
Signal drawing view	Draw waveforms, time axis, cursor, upper and lower limit of waveforms																											
Signal management view	<p>Set the length of time axis, signal location, waveform color, waveform line, upper and lower limit of signals. The list for signal management view is defined as follows:</p> <table border="1"> <thead> <tr> <th>Column</th><th>Name</th><th>Meaning</th></tr> </thead> <tbody> <tr> <td>1</td><td>Null</td><td>Signal waveform whether or not shown</td></tr> <tr> <td>2</td><td>Null</td><td>Signal waveform color</td></tr> <tr> <td>3</td><td>Signal name</td><td>Signal name</td></tr> <tr> <td>4</td><td>Connection state</td><td>Whether the inverter is connected to the upper computer</td></tr> <tr> <td>5</td><td>Device state</td><td>Inverter state</td></tr> <tr> <td>6</td><td>Current value</td><td>The value at the right end of signal waveform, the newest collected data in oscilloscope</td></tr> <tr> <td>7</td><td>L-value</td><td>The value of corresponding signal of left cursor at the point of time</td></tr> <tr> <td>8</td><td>R-value</td><td>The value of corresponding signal of right cursor at the point of time</td></tr> </tbody> </table>	Column	Name	Meaning	1	Null	Signal waveform whether or not shown	2	Null	Signal waveform color	3	Signal name	Signal name	4	Connection state	Whether the inverter is connected to the upper computer	5	Device state	Inverter state	6	Current value	The value at the right end of signal waveform, the newest collected data in oscilloscope	7	L-value	The value of corresponding signal of left cursor at the point of time	8	R-value	The value of corresponding signal of right cursor at the point of time
Column	Name	Meaning																										
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2	Null	Signal waveform color																										
3	Signal name	Signal name																										
4	Connection state	Whether the inverter is connected to the upper computer																										
5	Device state	Inverter state																										
6	Current value	The value at the right end of signal waveform, the newest collected data in oscilloscope																										
7	L-value	The value of corresponding signal of left cursor at the point of time																										
8	R-value	The value of corresponding signal of right cursor at the point of time																										

Name		Function		
				point of time
		9	Difference	The value of corresponding signal of left cursor minus the value of corresponding signal of right cursor
		10	Interval of time	The interval of time between right and left cursor
		11	Max	The maximum value in signal data
		12	Min	The minimum value in signal data
		13	Unit	-

Signal management view Toolbar:



Column	Name	Meaning
1	Start	see 6.2
2	Pause	see 6.2
3	Stop	see 6.2
4	Previous waveform	see 6.3
5	The current waveform of forward 1/4	see 6.3
6	The current waveform back page 1/4	see 6.3
7	Next waveform	see 6.3
8	Waveform selection enable	see 6.4
9	X Timeline	see 6.5
10	The counter enable	-
11	Add the oscilloscopic channel	see 6.6
12	Delete the oscilloscopic channel	see 6.6
13	Signal channel up	-
14	Signal channel down	-
15	Fault waveform	see 6.7
16	Open the history waveform	-
17	Save waveform	See 6.8
18	Full screen / normal	-

## 6.2 Start, pause and stop oscilloscope

When the signals are added to signal management list and the device state is connected,

click the activated  icon, the system will begin collecting data and drawing

waveforms. In order to analyze a segment of waveforms without stopping collecting data,

click the  icon, the oscilloscope will stop refreshing waveforms and continue

collecting data. After the completion of collecting data, click the  icon, the system will stop refreshing waveforms and collecting data.

### 6.3 Shifting and playback of waveform segments

Wave segments are the waveforms at the time when the oscilloscope starts and stops. Multiple waveform segments are saved in the same file. Shift to the previous segment by

clicking the  icon and to the next segment by clicking the  icon.

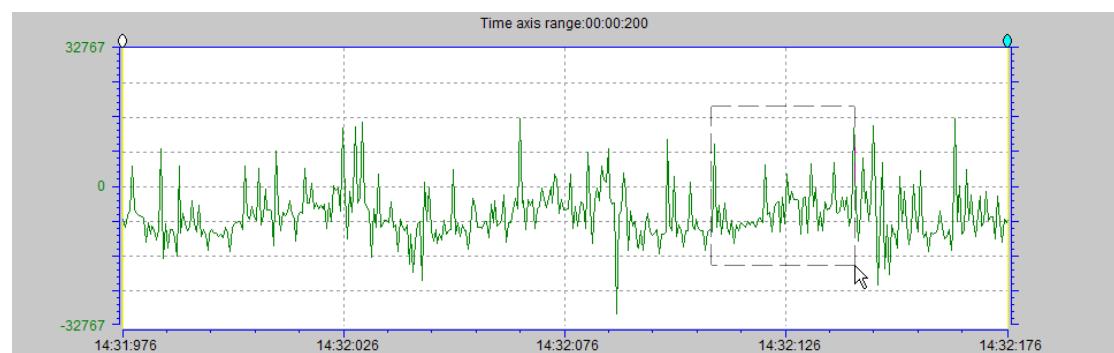
Playback function is applied when the waveform segment cannot be totally displayed at a certain range of time axis. Users can play back the waveform 1/4 of time axis range before

by clicking the  icon and the waveform 1/4 of time axis range after by clicking the  icon.

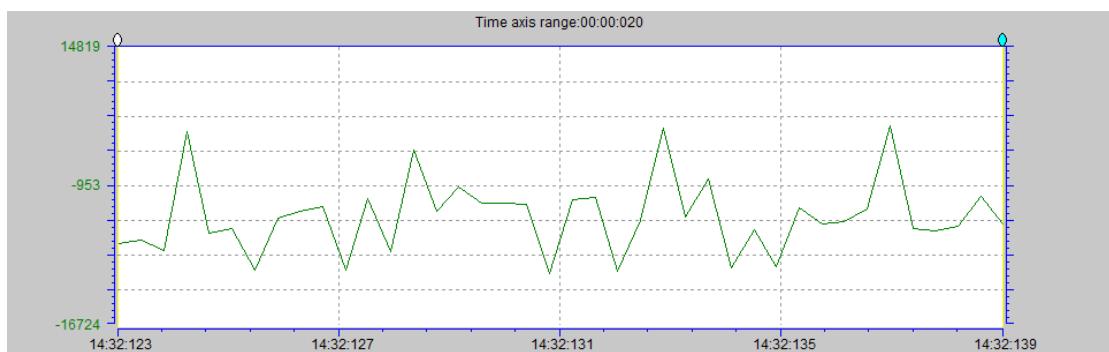
### 6.4 Selection

Select a region of waveforms by mouse, then zoom in to the whole drawing view and right click to return to original waveforms. Hold down the left mouse button at the start point (in waveform drawing view), drag the mouse to select a region and finally release.

Before selection:

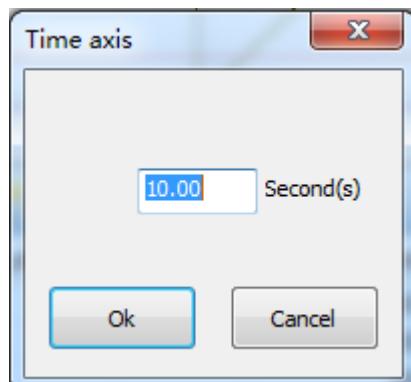


After selection:



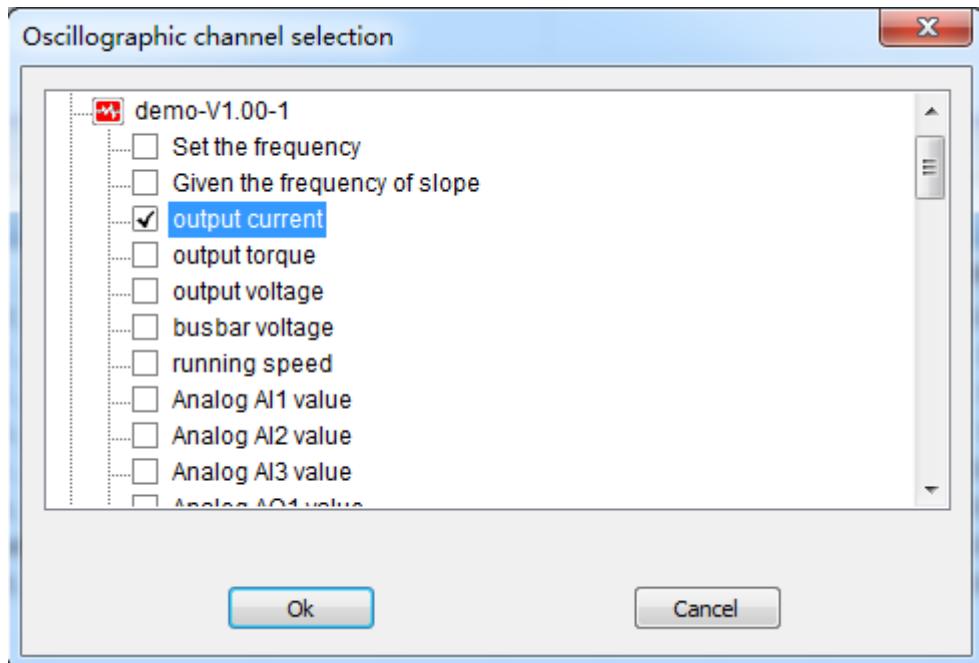
## 6.5 Time axis

Users can click the  icon in signal control toolbar to modify the time axis.



## 6.6 Add and delete signals

Add signals to signal management list. The system will collect the data of the signals after the oscilloscope starts. Adding signals is available in oscilloscope. Click  icon in signal control toolbar and pop up the dialog box of add signals. Single click the checkbox, '√' indicates the signal is selected; click again, the selection is canceled. Then single click OK button. Note: The added signals will no longer appear in the signal list. When connected to a single inverter software time add up to 10 signals, connecting more than one inverter can only add 20 at a time.



Delete signals from signal management list, together with attributes and data. Deleting signals is available in oscillography. Select the signals that need to be deleted, then click



icon in signal control toolbar.

## 6.7 Fault waveform

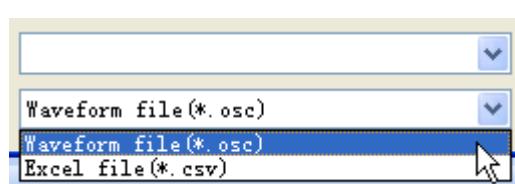
To find the causes of faults, the inverter saves the running data of 200ms before the fault..



Click the  icon in signal control toolbar, extract the fault waveforms automatically and display on the oscillograph.

## 6.8 Save waveforms

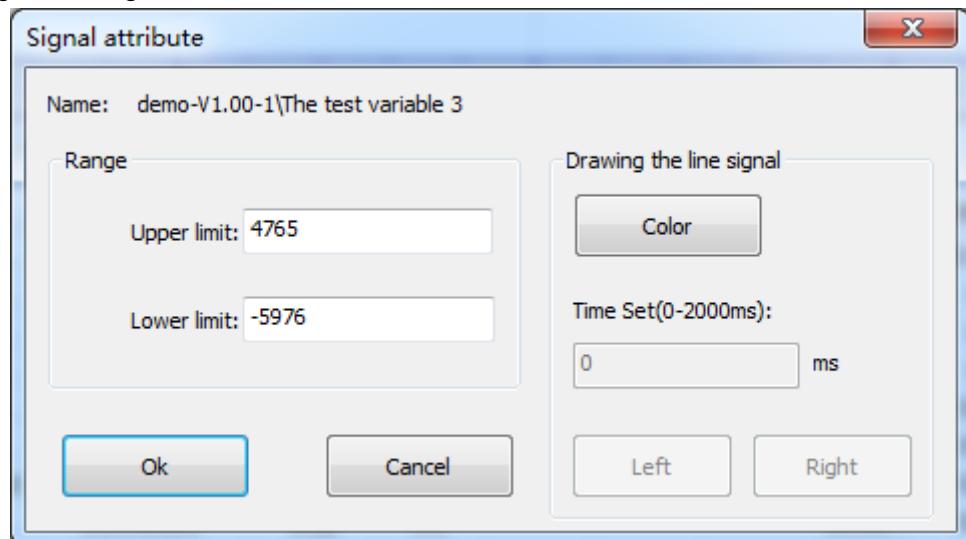
To save the collected signal data, click the  icon in toolbar and pop up the dialog box of save file.



There are two ways to save files, in self-defined files (\*.osc) or comma-separated files (\*.csv).

## 6.9 Signal attribute setting

Adjust the waveform color and line to analyze the signal data. In the list of signal management view, double click the option of signals that needs setting and pop up the dialog box of signal attribute.



## 6.10 Left and right cursor

Obtain all signals values at the same point of time, difference between the corresponding signal values and the interval of time between left and right cursor. The cursor facilitates users analyzing the signal data. The mouse pointer is in the circle of the cursor. By holding down the mouse pointer, the cursor can be dragged to move left and right. Operate fine tuning via left and right keypad button.

## VII. HotKey

Help	F1
Login factory function group	F3
Logout factory function group	F4
Refresh function codes	F5
Full-screen switch	F11

## VIII. Trouble shooting

The software may have some problems during operation and corresponding solutions are shown below. If you cannot solve the problems, please contact with local dealers or SALICRU offices.

Common problems	Causes	Solutions
Connecting serial port failed	The computer has no serial port.	Check computer configuration.
	The number of serial port is incorrect.	System attribute-hardware-device manager: check the serial port NO., then set the serial port NO. of upper computer.
	Serial port is occupied.	Check the opened software and close the software occupying the serial port.
Adding inverter failed	Parameter setting of serial port does not match.	Check whether the set parameter of serial port of upper computer is the same as that of inverter.
	Wrong slave address of serial port	Check Modbus communication address of the inverter.
	USB-to-RS485 converter does not match.	Replace computer or converter.
	Inverter type cannot be recognized.	Check the inverter type supported by the system.
Adding inverter failed Unable to control inverter Unable to set communication set value Unable to start oscilloscope	Running command channel is not set to communication command channel.	Check the manual and set running command channel to communication command channel.
	Control station is not selected.	Select control station properly.
	Communication setting is controlled by the setting mode.	Check the manual and set the corresponding mode.
	The configuration table and inverter do not match.	Update the configuration table.

No waveforms after the oscillograph starts	The operating system's firewall	In Windows 7 system must close the firewall, or when the firewall prompts the pop-up dialog box don't choose "cancel".
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